Phenomenological applications of the 2PI Hartree approximation

Gergely Fejős

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- Renormalisation of the gap equations and the equation of state in general models
- The method of constructing the counter-terms for invariant tensor structures
- \blacktriangleright Example 1: SU(N)× SU(N) meson model, focusing on N= 3 and N $\rightarrow \infty$
- Example 2: $U(3) \times U(3)$ meson model
- Solving the renormalised equations using phenomenological input
- Mass spectra at zero temperature

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Renormalisation

► Consider a general Lagrangian: $L = \frac{1}{2} [\partial_{\mu} \sigma_{a} \partial^{\mu} \sigma_{a} + \partial_{\mu} \pi_{a} \partial^{\mu} \pi_{a} - \mu_{S}^{2} \sigma_{a} \sigma_{a} - \mu_{P}^{2} \pi_{a} \pi_{a}] - \frac{1}{3} F_{abcd}^{S} \sigma_{a} \sigma_{b} \sigma_{c} \sigma_{d} - \frac{1}{3} F_{abcd}^{P} \pi_{a} \pi_{b} \pi_{c} \pi_{d} - 2H_{ab,cd} \pi_{a} \pi_{b} \sigma_{c} \sigma_{d}$

► It fits the O(N), and also the SU(N)×SU(N) model with $M = T_a(\sigma_a + i\pi_a)$

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- It fits the O(N), and also the SU(N)×SU(N) model with M= T_a(σ_a + iπ_a)
- It is assumed, that only the sigma field has non-zero expectation value
- ► The 2PI effective potential is the following: $V = \frac{1}{2}\mu_{ab,S}^2 \bar{\sigma}_a \bar{\sigma}_b + \frac{1}{3}F_{abcd}^S \bar{\sigma}_a \bar{\sigma}_b \bar{\sigma}_c \bar{\sigma}_d - \frac{i}{2}\int_k [D_{ab}^{-1S}G_{ba}^S + D_{ab}^{-1P}G_{ba}^P] - -\frac{i}{2}\int_k [lnG_{aa}^{-1S} + lnG_{aa}^{-1P}] + V_2 + V^{ct}$

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- In Hartree approximation V₂ contains the double bubble diagrams in the theory
- V^{ct} contains the counter-terms

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Renormalisation

• Counter-term structure: $V^{\text{ct}} = V_4^{\text{ct}} + V_2^{\text{ct}} + V_0^{\text{ct}}$

$$\blacktriangleright V_4^{\text{ct}} = \frac{1}{2} \delta \tilde{\mu}_{ab,S}^2 \bar{\sigma}_a \bar{\sigma}_b + \frac{1}{3} \delta \tilde{F}_{abcd} \bar{\sigma}_a \bar{\sigma}_b \bar{\sigma}_c \bar{\sigma}_d$$

- $V_2^{\text{ct}} = \frac{1}{2} \delta \hat{\mu}_{ab,S}^2 \int_k G_{ba}^S(k) + \frac{1}{2} \delta \hat{\mu}_{ab,P}^2 \int_k G_{ba}^P(k) + 4\delta \hat{F}_{abcd} \int_k G_{ab}^S(k) \bar{\sigma}_c \bar{\sigma}_d + 4\delta \hat{H}_{abcd} \int_k G_{ab}^P(k) \bar{\sigma}_c \bar{\sigma}_d$
- ► $V_0^{\text{ct}} = \delta F_{abcd}^S \int_k G_{ab}^S(k) \int_p G_{cd}^S(p) + \delta F_{abcd}^P \int_k G_{ab}^P(k) \int_p G_{cd}^P(p) + 2\delta H_{abcd} \int_k G_{ab}^S(k) \int_p G_{cd}^P(p)$
- 9 different counter tensors

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- 9 different counter tensors
- ► The stationary conditions: $\frac{\delta V}{\delta G_{ab}^{P,S}} = 0$, $\frac{\delta V}{\delta \bar{\sigma}_a} = 0$ give the gap equations and the equation of state
- ► One has to separate the finite parts from the divergences, in the tadpole integrals M₀ renormalisation scale has to be introduced

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▶ With the notation $M_{cd}^{S,P} = O_{ce}^{S,P} O_{de}^{S,P} \tilde{M}_{e}^{2}, \quad \int_{k} G_{cd}^{S,P} = O_{ce}^{S,P} O_{de}^{S,P} T(\tilde{M}_{S;P,e}^{2}),$ the finite parts are:

 ▶ P gap: M²_{ab,P} = µ²_{ab,P} + 4H_{abcd} O^S_{ce} O^S_{de} T_F(M²_{S,e}) + 4F^P_{abcd} O^P_{ce} O^P_{de} T_F(M²_{P,e})

 ▶ S gap: M²_{ab,S} = µ²_{ab,S} + 4F^S_{abcd} σ_c σ_d + 4F^S_{abcd} O^S_{ce} O^S_{de} T_F(M²_{S,e}) + 4H_{abcd} O^P_{ce} O^P_{de} T_F(M²_{P,e})

 ▶ Eq. of state: M²_{ab,S} σ_b = ⁸/₃ F^S_{abcd} σ_b σ_c σ_d

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- ▶ P gap: $M_{ab,P}^2 = \mu_{ab,P}^2 + 4H_{abcd}O_{ce}^SO_{de}^ST_F(\tilde{M}_{S,e}^2) + 4F_{abcd}^PO_{ce}^PO_{de}^PT_F(\tilde{M}_{P,e}^2)$ ▶ S gap: $M_{ab,S}^2 = \mu_{ab,S}^2 + 4F_{abcd}^S\bar{\sigma}_c\bar{\sigma}_d + \frac{1}{2}F_{abcd}^S\bar{\sigma}_c\bar{\sigma}_d + \frac{1}{2}F_{abcd}^S\bar{\sigma}$
 - $4F_{abcd}^{S}O_{ce}^{S}O_{de}^{S}T_{F}(\tilde{M}_{S,e}^{2}) + 4H_{abcd}O_{ce}^{P}O_{de}^{P}T_{F}(\tilde{M}_{P,e}^{2})$
- Eq. of state: $M^2_{ab,S}\bar{\sigma}_b = \frac{8}{3}F^S_{abcd}\bar{\sigma}_b\bar{\sigma}_c\bar{\sigma}_d$
- ► Types of divergences: ā independent, ā dependent overall divergences, T_F dependent subdivergences → it must be ensured that all types of these expressions vanish

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- $\delta F_{abcd}^{S}, \delta F_{abcd}^{P}, \delta H_{abcd}$ determines $\delta \hat{F}_{abcd}, \delta \hat{H}_{abcd}$ and $\delta \tilde{F}_{abcd}$
- ▶ The 3 mass counter tensors can be expressed with the above 6

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- ▶ The 3 mass counter tensors can be expressed with the above 6
- ► The non-trivial problem is to solve the following equations:

$$\left(\delta F_{abmn}^{S/P} + 4T_d [(F_{abcd}^{S/P} + \delta F_{abcd}^{S/P}) F_{cdmn}^{S/P} + (H_{ab,cd} + \delta H_{ab,cd}) H_{cd,mn}] \right) O_{me}^{S/P} O_{ne}^S T_F (\tilde{M}_{S/P,e}^2) = 0$$

$$\left(\delta H_{ab,mn} + 4T_d [(F_{abcd}^{S/P} + \delta F_{abcd}^{S/P}) H_{cd,mn} + (H_{ab,cd} + \delta H_{ab,cd}) F_{cd,mn}^{P/S}] \right) O_{me}^{P/S} O_{ne}^{P/S} T_F (\tilde{M}_{P/S,e}^2) = 0$$

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- The non-trivial problem is to solve the following equations:
- $\left(\delta F_{abmn}^{S/P} + 4T_d [(F_{abcd}^{S/P} + \delta F_{abcd}^{S/P})F_{cdmn}^{S/P} + (H_{ab,cd} + \delta H_{ab,cd})H_{cd,mn}] \right) O_{me}^{S/P} O_{ne}^S T_F(\tilde{M}_{S/P,e}^2) = 0$ $\left(\delta H_{sb} + 4T_s [(F_{abcd}^{S/P} + \delta F_{abcd}^{S/P})H_{sb} + (H_{sb}) + (H_{sb}) + (H_{sb}) \right)$
- $\left(\frac{\delta H_{ab,mn} + 4T_d [(F_{abcd}^{S/P} + \delta F_{abcd}^{S/P})H_{cd,mn} + (H_{ab,cd} + \delta H_{ab,cd})F_{cd,mn}^{P/S}] \right) O_{me}^{P/S} O_{ne}^{P/S} T_F(\tilde{M}_{P/S,e}^2) = 0$
- Assuming that the the spectrum contains enough different masses, the projecting is irrelevant

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 The coupling and the counter tensors are linear combinations of independent rank-4 invariant tensors (t^a) of the symmetry group

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$$F_{abcd}^{S/P} = \sum_{\alpha} f_{\alpha}^{S/P} t_{abcd}^{\alpha}, \quad H_{abcd} = \sum_{\alpha} h_{\alpha} t_{abcd}^{\alpha}$$

► $\delta F_{abcd}^{S/P} = \sum_{\alpha} \delta f_{\alpha}^{S/P} t_{abcd}^{\alpha}, \quad \delta H_{abcd} = \sum_{\alpha} \delta h_{\alpha} t_{abcd}^{\alpha}$

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- The coupling and the counter tensors are linear combinations of independent rank-4 invariant tensors (t^α) of the symmetry group
- $F_{abcd}^{S/P} = \sum_{\alpha} f_{\alpha}^{S/P} t_{abcd}^{\alpha}, \quad H_{abcd} = \sum_{\alpha} h_{\alpha} t_{abcd}^{\alpha}$ • $\delta F_{abcd}^{S/P} = \sum_{\alpha} \delta f_{\alpha}^{S/P} t_{abcd}^{\alpha}, \quad \delta H_{abcd} = \sum_{\alpha} \delta h_{\alpha} t_{abcd}^{\alpha}$
- ► It is useful to work out a multiplication table for these invariants: $t^{\alpha}_{abcd} t^{\beta}_{cdef} = \sum_{\gamma} \frac{g_{\alpha\beta\gamma}}{g_{\alpha\beta\gamma}} t^{\gamma}_{abef}$
- After determing the g_{αβγ} coefficients, δf_α^{S/P}, δh_α counterterms can be easily expressed, since the equations are linear

 In this model the four-point coupling tensors F^{S/P}_{abcd} and H_{abcd} can be written in the following form: F^S_{abcd} = F^P_{abcd} = ^{g₁}/₄δ_{ab}δ_{cd} + ^{g₁}/₄(δ_{ac}δ_{bd} + δ_{ad}δ_{bc}) + ^{g₂}/₈d_{abm}d_{cdm} + ^{g₂}/₈ + (d_{acm}d_{bdm} + d_{adm}d_{bcm})
 H_{ab,cd} = ¹/₄(g₁ + ^{2g₂}/_N)δ_{ab}δ_{cd} - ^{g₂}/_{4N}(δ_{ac}δ_{bd} + δ_{ad}δ_{bc}) + ^{3g₂}/₈d_{abm}d_{cdm} - ^{g₂}/₈(d_{acm}d_{bdm} + d_{adm}d_{bcm})
 Definition of d tensors: {λ_i, λ_i} = ⁴/_{4N}δ_{ii} + 2d_{iik}λ_k

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- In this model the four-point coupling tensors F^{S/P}_{abcd} and H_{abcd} can be written in the following form: F^S_{abcd} = F^P_{abcd} = g₁/4 δ_{ab}δ_{cd} + g₁/4 (δ_{ac}δ_{bd} + δ_{ad}δ_{bc}) + g₂/8 d_{abm}d_{cdm} + g₂/8 + (d_{acm}d_{bdm} + d_{adm}d_{bcm})
 H_{ab,cd} = 1/4 (g₁ + 2g₂/N)δ_{ab}δ_{cd} - g₂/4N (δ_{ac}δ_{bd} + δ_{ad}δ_{bc}) + 3g₂/8 d_{abm}d_{cdm} - g₂/8 (d_{acm}d_{bdm} + d_{adm}d_{bcm})
 Definition of d tensors: {λ_i, λ_i} = 4/N δ_{ii} + 2d_{iik}λ_k
- ▶ The indicated set of 4 invariants is closed under multiplication

- In this model the four-point coupling tensors F^{S/P}_{abcd} and H_{abcd} can be written in the following form:
 - $F_{abcd}^{S} = F_{abcd}^{P} = \frac{g_{1}}{4} \delta_{ab} \delta_{cd} + \frac{g_{1}}{4} (\delta_{ac} \delta_{bd} + \delta_{ad} \delta_{bc}) + \frac{g_{2}}{8} d_{abm} d_{cdm} + \frac{g_{2}}{8} + (d_{acm} d_{bdm} + d_{adm} d_{bcm})$
- $H_{ab,cd} = \frac{1}{4} (g_1 + \frac{2g_2}{N}) \delta_{ab} \delta_{cd} \frac{g_2}{4N} (\delta_{ac} \delta_{bd} + \delta_{ad} \delta_{bc}) + \frac{3g_2}{8} d_{abm} d_{cdm} \frac{g_2}{8} (d_{acm} d_{bdm} + d_{adm} d_{bcm})$
- Definition of *d* tensors: $\{\lambda_i, \lambda_j\} = \frac{4}{N} \delta_{ij} + 2d_{ijk}\lambda_k$
- The indicated set of 4 invariants is closed under multiplication
- Special case N= 3: there are only 3 invariants, because of the relation:

 $d_{abm}d_{cdm} + d_{acm}d_{bdm} + d_{adm}d_{bcm} = \frac{1}{3}(\delta_{ab}\delta_{cd} + \delta_{ac}\delta_{bd} + \delta_{ad}\delta_{bc})$

One realises that δF^P = δF^S, therefore there are 6 counter terms: δf₁, δf₂, δf₃, δh₁, δh₂, δh₃ and 6 equations

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- The equations are the following:
- ► $\delta f_1 = -8T_d[5f(f + \delta f_1) + f(f + \delta f_2) + 4h_1(h_1 + \delta h_1) + h_1(h_2 + \delta h_2) + h_2(h_1 + \delta h_1)]$
- $\bullet \ \delta f_2 = -8T_d[f(f+\delta f_2)+h_2(h_2+\delta h_2)]$
- $\delta f_3 = -8T_d[f\delta f_3 + h_3(h_2 + \delta h_2) + (h_2 + 5h_3/6)(h_3 + \delta h_3)]$
- $\delta h_1 = -8T_d[(4h_1 + h_2)(f + \delta f_1) + h_1(f + \delta f_2) + 5f(h_1 + \delta h_1) + f(h_2 + \delta h_2)]$
- $\bullet \ \delta h_2 = -8 T_d [h_2 (f + \delta f_2) + f (h_2 + \delta h_2)]$
- $\delta h_3 = -8T_d[h_3(f + \delta f_2) + \delta f_3(h_2 + 5h_3/6) + f(h_3 + \delta h_3)]$

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- $\bullet \ \delta h_2 = -8 T_d [h_2 (f + \delta f_2) + f (h_2 + \delta h_2)]$
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- They are linear, easy to solve them

$\mathsf{SU}(\mathsf{N}){\times}\mathsf{SU}(\mathsf{N})$ meson model, $\mathsf{N}\to\infty$ case

- The general SU(N) tensors' multiplication table contains only one product which scales with N², this is the only one which counts while solving the equations for counter terms
- $\bullet \ \delta_{ab}\delta_{cd}*\delta_{cd}\delta_{ef} = (N^2 1)\delta_{ab}\delta_{ef}$

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- $\bullet \ \delta_{ab}\delta_{cd}*\delta_{cd}\delta_{ef} = (N^2 1)\delta_{ab}\delta_{ef}$
- ▶ In this case there will be 2 counter terms: δf_1 , δh_1
- $\delta f_1 + 4 T_d N^2 ((f_1 + \delta f_1) f_1 + (h_1 + \delta h_1) h_1) = 0$
- $\delta h_1 + 4 T_d N^2 ((f_1 + \delta f_1) h_1 + (h_1 + \delta h_1) f_1) = 0$

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- $\delta h_1 + 4 T_d N^2 ((f_1 + \delta f_1) h_1 + (h_1 + \delta h_1) f_1) = 0$
- ► Since at large $N f_1 = h_1 = g_1/4$, one can consistently choose $\delta h_1 = \delta f_1 =: \delta g_1 \rightarrow$ one single counterterm is enough to renormalise the theory
- We get $\delta g_1 = -\frac{2N^2 T_d g_1^2}{1+2N^2 T_d g_1}$, which coincides with the O(2N²) model's coupling counterterm at large N

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- ► The group algebra modifies as: $\{\lambda_a, \lambda_b\} = d_{abc}\lambda_c$ with $d_{ab0} = \sqrt{\frac{2}{N}}\delta_{ab}$
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- U(3) can also be interpreted as a direct product of an SU(3) and a U(1) groups
- ► The *F* and *H* tensors can not be expressed with 3 invariant tensors closing under multiplication

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- U(3) can also be interpreted as a direct product of an SU(3) and a U(1) groups
- ► The *F* and *H* tensors can not be expressed with 3 invariant tensors closing under multiplication
- The minimum set of invariants has to contain 9 invariant tensors
- It means that 18 different counter terms have to be determined

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▶ The used invariant tensors:

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$$t_{abcd}^1 = \delta_{ab}\delta_{cd}(1 - \delta_{a0})(1 - \delta_{b0})(1 - \delta_{c0})(1 - \delta_{d0}),$$

 $t_{abcd}^2 = (\delta_{ac}\delta_{bd} + \delta_{ad}\delta_{cb})(1 - \delta_{a0})(1 - \delta_{b0})(1 - \delta_{c0})(1 - \delta_{d0}),$
 $t_{abcd}^3 = d_{abm}d_{cdm}(1 - \delta_{a0})(1 - \delta_{b0})(1 - \delta_{c0})(1 - \delta_{d0}),$

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 $t_{abcd}^3 = d_{abm}d_{cdm}(1 - \delta_{a0})(1 - \delta_{b0})(1 - \delta_{c0})(1 - \delta_{d0}),$
► $t_{abcd}^4 = \delta_{ab}(1 - \delta_{a0})(1 - \delta_{b0})\delta_{c0}\delta_{d0},$
 $t_{abcd}^5 = \delta_{cd}(1 - \delta_{c0})(1 - \delta_{c0})\delta_{a0}\delta_{b0},$
 $t_{abcd}^6 = \delta_{ad}\delta_{b0}\delta_{c0}(1 - \delta_{a0})(1 - \delta_{d0}) + \delta_{ac}\delta_{b0}\delta_{d0}(1 - \delta_{a0})(1 - \delta_{c0}) + \delta_{bd}\delta_{a0}\delta_{c0}(1 - \delta_{b0})(1 - \delta_{d0}) + \delta_{bc}\delta_{a0}\delta_{d0}(1 - \delta_{b0})(1 - \delta_{c0}),$
 $t_{abcd}^7 = d_{acd}\delta_{b0}(1 - \delta_{a0})(1 - \delta_{c0})(1 - \delta_{d0}) + d_{abd}\delta_{c0}(1 - \delta_{a0})(1 - \delta_{b0})(1 - \delta_{d0}),$
 $t_{abcd}^8 = d_{abc}\delta_{d0}(1 - \delta_{a0})(1 - \delta_{b0})(1 - \delta_{c0}) + d_{abd}\delta_{d0}(1 - \delta_{a0})(1 - \delta_{b0})(1 - \delta_{c0}),$

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The used invariant tensors:

Solving the finite gap equations and the equation of state

The earlier model can be extended:

$$\Delta L = c \left[det(\lambda_a(\sigma_a + i\pi_a)) + det(\lambda_a(\sigma_a + i\pi_a))^{\dagger} \right] + Tr \left[\lambda_a h_a \left(\lambda_b(\sigma_b + i\pi_b) + (\lambda_b(\sigma_b + i\pi_b))^{\dagger} \right) \right]$$

▶ The non-zero expectation values are set to: $\bar{\sigma}_0$, $\bar{\sigma}_8$

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- ▶ The non-zero expectation values are set to: $\bar{\sigma}_0$, $\bar{\sigma}_8$
- In this case the model's parameters are: c, μ, g₁, g₂, h₀, h₈, M₀, T
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- ► There are 8 gap equations + 2 equations for the angles of the diagonalizing matrices + 2 equations of state → 12 equations have to be solved simultaneously
- The main goal is to get the condensates and the masses as a function of the temperature
- ► The first step: parametrisation → change the variables, fix 4 masses at zero temperature and a given renormalisation scale

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- Renormalization procedure for various types of multicomponent scalar models
- The explicit construction of the counter terms
- ▶ 2 examples: $SU(N) \times SU(N)$ and $U(3) \times U(3)$ models
- Solving the finite equations, the mass spectrum scale dependence at zero temperature
- ▶ Near future: thermodynamics

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